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2008 J. Phys.: Condens. Matter 20224022
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# Nonlinear rotational waves in a molecular chain 

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Received 8 November 2007, in final form 19 December 2007
Published 13 May 2008
Online at stacks.iop.org/JPhysCM/20/224022


#### Abstract

A molecular chain with rotational degrees of freedom and quadrupolar interaction between linear molecules is investigated theoretically. Rotation of the molecules is in the plane of an adsorbing surface only and their centres of gravity are pinned. Continual nonlinear wave equations are derived for the rotational excitations of the molecules from the discrete ones. The oscillations of the molecules near the equilibrium positions are investigated. The interactions are expanded in powers of angles and nonlinear terms are accounted for. Dispersion is considered to be small. The normal modes are found to split the initial entangled nonlinear system into two independent equations. A Linear equation describes waves of the stiffer normal mode. A nonlinear equation describes waves of the softer normal mode. A nonlinear Schrödinger equation is derived for waves of the softer normal mode, and a solution for nonlinear waves is obtained.


## 1. Introduction

Molecular crystals have been investigated extensively because of their unusual electric and thermal conductivity and structural properties [1, 2]. Molecular cryocrystals [2] are interesting for applications in low temperature techniques, and they have the simplest molecules with well known interactions. A considerable number the properties of molecular crystals are connected with rotation of their molecules or molecular fragments which, in the case of a linear configuration, are described by the rigid rotors model. However, molecular cryocrystals, as almost model objects, have a complicated crystal structure with some sublattices and space rotor rotation. A considerable simplification of their description, while still keeping the basic physical features, is found by application of chain models to the linear lattice dynamics and thermodynamics of molecular cryocrystals [2].

Low dimensional systems are very important as models as well as objects for applications. Real objects can be adsorbed structures [3] or layered crystals [4]. Chain models are a necessary stage in the investigation of the dynamics and thermodynamics of more complex systems: crystals [5], nonlinear dynamics of atomic and molecular lattices [6] and their thermal conductivity [7]. The complexity of models even for a 1D molecular chain requires some approximations
to simplify the system description. Such approximations are in the model potential and 1D rotation of the molecular rotors [2, 3, 7]. After these essential simplifications, analytical consideration is constricted by the limits of small oscillation or free rotation of rotors, i.e. the limits of low and high energies. In the middle range of energies, especially in the vicinity of the point of orientational melting, an analytical description of the molecular rotor dynamics and thermodynamics is absent.

In the present paper we investigate the rotational nonlinear wave excitations of an ordered molecular chain in the range from the low energy limit to the point of orientational melting. The molecular chain consists of linear molecules with realistic quadrupolar interaction [2]. It was natural to begin investigation of this complex problem starting from simpler cases such as linear rotational oscillations [8, 9] or the longwave limit for arbitrary amplitudes and nonlinearity [10] in our previous works. Here we use the same model approximations as in $[8-10]$ and earlier in $[2,3]$ : one degree of freedom for each molecule, and very hard translational potential, so translational modes are frozen and can be neglected. The rotational potential energy was obtained by supposing nearest neighbour interaction only; the next neighbour contribution is much less. The molecular chain energy was found to have a
minimum value for alternating ordering of the molecules:

$$
\begin{gather*}
\left(\phi_{2 n}=\pi / 2+\pi j ; \phi_{2 n+1}=\pi j\right) \quad \text { or } \\
\quad\left(\phi_{2 n}=\pi j ; \phi_{2 n+1}=\pi / 2+\pi j\right) . \tag{1}
\end{gather*}
$$

Here $i, j, n=0, \pm 1, \pm 2, \ldots$, an angle $\phi_{i}$ is between the principal axis of a molecule and the direction of the radiusvector which connects the centres of inertia of the $i$ th and $(i+1)$ th molecules. Therefore, the molecular system splits into two sublattices and index $i=2 n(i=2 n+1)$ defines an even (odd) site. To research the time or space evolution of the molecular chain we must write the Lagrangian $L=K-U$ of the system. Here $U$ and $K=\frac{1}{2} \sum J_{i} \dot{\phi}_{i}^{2}$ are potential and kinetic energies of the chain, the $i$ th molecule has moment of inertia $J_{i}=J_{0}$ and angular velocity $\dot{\phi}_{i}$. Then the Lagrangian variation yields a system of equations for the chain motion in even $\left(\phi_{2 m}\right)$ and odd ( $\psi_{2 m+1}$ ) sites:

$$
\begin{align*}
\ddot{\phi}_{i}- & \left\{2 a \sin 2 \phi_{i}+b\left[\sin 2\left(\phi_{i}-\psi_{i-1}\right)+\sin 2\left(\phi_{i}-\psi_{i+1}\right)\right]\right. \\
& \left.+c\left[\sin 2\left(\phi_{i}+\psi_{i-1}\right)+\sin 2\left(\phi_{i}+\psi_{i+1}\right)\right]\right\}=0 ; \\
\ddot{\psi}_{i+1} & -\left\{2 a \sin 2 \psi_{i+1}+b\left[\sin 2\left(\psi_{i+1}-\phi_{i}\right)\right.\right.  \tag{2}\\
& \left.+\sin 2\left(\psi_{i+1}-\phi_{i+2}\right)\right]+c\left[\sin 2\left(\psi_{i+1}+\phi_{i}\right)\right. \\
& \left.\left.+\sin 2\left(\psi_{i+1}+\phi_{i+2}\right)\right]\right\}=0 .
\end{align*}
$$

Here the parameters of quadrupolar-quadrupolar interaction are $a=5 / 4, b=3 / 8, c=35 / 8, \Gamma=3 Q^{2} / 4 R_{0}^{5}$, where $Q$ is a quadrupolar moment of a molecule and $R_{0}$ is a distance between centres of inertia of the molecules. The dimensionless time is introduced: $t \rightarrow \tau=t \omega_{0}$ where $\omega_{0}^{2}=\Gamma / J_{0}$ is a characteristic frequency.

Stability of the structure (1) was confirmed by analysis of the dynamical equations (2) as in the linear approximation $[8,9]$ and the long-wave limit for arbitrary amplitudes and nonlinearity [10] when all even or odd sites are equivalent. Previously we found the rotational excitations demonstrate a strong anisotropy in the angle space-directions of easy excitation ('valleys' on the effective potential) exist. By accounting for the strong anisotropy, it is possible to consider linear and nonlinear oscillations separately.

## 2. The continual equations for an inhomogeneous chain

The system of equations (2) is strongly nonlinear and differential-difference. Let us rewrite these equations for the two subsystems that follows from separation of the molecules into two sublattices and introduce new variables. Transformation from a discrete to a continual system of equations is not unambiguous. We suggest some set of steps (ansatz) which have to lead to a proper result.
(1) Here we use more convenient variables to account for the difference between the sites. It is natural to begin investigation of this complex problem by starting from the limiting case of small oscillations of molecules around the equilibrium positions [8, 9]. With this purpose new variables were introduced by the relations $\phi_{2 m}=v_{2 m} ; \phi_{2 m+1}=\pi / 2+$ $u_{2 m+1}$, where $v_{2 m}$ and $u_{2 m+1}$ are small deviations of the angles
from the equilibrium positions. After expansion of terms as power series in small perturbations $v$ and $u$, the set of equations for the motion can be transformed into a linear system of differential-difference equations [8, 9]. Now we account for the cubic contributions in this expansion.
(2) Let us find expansion of the variables $v$ and $u$ around values in the $i$ th and $i+1$ th sites. Then we introduce the dimensionless space coordinate:

$$
\begin{equation*}
\xi=\frac{x}{R_{0}} \tag{3}
\end{equation*}
$$

Let us note that $\Delta x=2 R_{0}$ and $\Delta \xi=2$. Then expansions can be written as $v_{i+2}=v_{i}+2 v_{i}^{\prime}+2 v_{i}^{\prime \prime} ; u_{i-1}=u_{i+1}-2 u_{i+1}^{\prime}+$ $2 u_{i+1}^{\prime \prime}$. Here derivations are $v^{\prime}=\partial v / \partial \xi$ and $v^{\prime \prime}=\partial^{2} v / \partial \xi^{2}$, the same formulae we have for $u, u^{\prime}, u^{\prime \prime}$. After substitution of expansions in the system (2) then grouping of the angles and their space derivations we obtain a system of continual dynamical nonlinear differential equations for the variables $v \equiv v_{2 m}$ and $u \equiv u_{2 m+1}$ :

$$
\begin{align*}
& \ddot{v}+b_{v} v+2 d u+d u^{\prime \prime}-\frac{2}{3} b_{v} v^{3}-4 d v^{2} u-4(b+c) v u^{2} \\
& \quad-\frac{4}{3} d u^{3}=0 ; \\
& \ddot{u}+b_{u} u+2 d v+d v^{\prime \prime}-\frac{2}{3} b_{u} u^{3}-4 d u^{2} v-4(b+c) u v^{2}  \tag{4}\\
& \quad-\frac{4}{3} d v^{3}=0 .
\end{align*}
$$

Here parameters are $b_{v}=4(-a+b+c)=14, b_{u}=4(a+$ $b+c)=24, d=2(c-b)=8$. We suppose relatively smooth changing of the orientation of the molecules. This means that derivations are relatively small: $v^{\prime \prime}, u^{\prime \prime} \ll v^{\prime}, u^{\prime} \ll v, u$. The system describes any nonlinear space- and time-dependent processes in the molecular chain for relatively large angular amplitudes.
(3) The attractive feature of the system (4) is symmetry in the coordinates $v, u$ and the interaction parameters under pair exchange:

$$
\begin{equation*}
v, b_{v} \longleftrightarrow u, b_{u} \tag{5}
\end{equation*}
$$

We will explore this symmetry and the properties of the parameters in further simplification of the equations and investigation of nonlinear excitations.

## 3. Integral of the equations for an inhomogeneous chain

(4) With the aim of further progress, let us consider inhomogeneous stationary excitations when $v$ and $u$ depend on $x-V t$. Here $V$ is velocity. In dimensionless variables we have $v(\zeta), u(\zeta) ; \zeta=\xi-w \tau$. Here $w=v / v_{0}$ is the dimensionless velocity and $v_{0}=R_{0} \omega_{0}$ is the characteristic one.

After introducing these coordinates the time-dependent terms are transformed into $\ddot{v} \rightarrow w^{2} v^{\prime \prime}$ and $\ddot{u} \rightarrow w^{2} u^{\prime \prime}$ where $v^{\prime \prime}=\partial^{2} v / \partial \zeta^{2}$ and $u^{\prime \prime}=\partial^{2} u / \partial \zeta^{2}$. Instead of the system of partial differential equations (4) we obtain the common differential one:

$$
\begin{align*}
& w^{2} v^{\prime \prime}+b_{v} v+2 d u+d u^{\prime \prime}-\frac{2}{3} b_{v} v^{3}-4 d v^{2} u-4(b+c) v u^{2} \\
& \quad-\frac{4}{3} d u^{3}=0 \\
& w^{2} u^{\prime \prime}+b_{u} u+2 d v+d v^{\prime \prime}-\frac{2}{3} b_{u} u^{3}-4 d u^{2} v  \tag{6}\\
& \quad-4(b+c) u v^{2}-\frac{4}{3} d v^{3}=0 .
\end{align*}
$$

The integral of this system still keeps symmetry, according to (5):

$$
\begin{align*}
& \frac{1}{2} w^{2}\left(v^{\prime 2}+u^{\prime 2}\right)+\frac{1}{2}\left(b_{v} v^{2}+b_{u} u^{2}\right)+2 d v u+d v^{\prime} u^{\prime} \\
& \quad-\frac{1}{6}\left(b_{v} v^{4}+b_{u} u^{4}\right)-\frac{4}{3} d v^{3} u-8(b+c) v^{2} u^{2} \\
& \quad-\frac{4}{3} d v u^{3}=C . \tag{7}
\end{align*}
$$

## 4. Normal modes equations and solutions

(5) The variables $v$ and $u$ are entangled in the nonlinear system of equations (4) and (6). Besides different variables have the same or very close amplitudes for linear [8, 9] and nonlinear [10] excitations of the molecular chain. Meanwhile introduction of the normal coordinates [9] splits the linear system of equations for the chain oscillations into two independent subsystems of oscillations; amplitudes of the obtained normal modes differ considerably. The linear system of equations can be obtained by omitting cubic terms in the nonlinear equations (4) and (6).

Let us introduce a normal coordinates for the linear subsystem of equations (6). Then both quadratic forms for variables $u, v$ and their derivations $u^{\prime}, v^{\prime}$ must be split in equations (6) and diagonalized in the integral (7). Operating with any of the equations (6) or (7) leads to the same result. We diagonalize the quadratic forms according [11]. The first step is diagonalization of the $u^{\prime}, v^{\prime}$ form. Let us introduce new variables by the coordinate rotation on the angle $\alpha_{1}$. Their substitution into (7) diagonalizes the $u^{\prime}, v^{\prime}$ quadratic form for

$$
\begin{equation*}
u=\frac{u_{1}+v_{1}}{\sqrt{2}} ; \quad v=\frac{u_{1}-v_{1}}{\sqrt{2}} \tag{8}
\end{equation*}
$$

Then after transformation (finding their sum and difference), each of equations (6) contains only one second derivation. The second step is the space deformation of variables with the purpose of obtaining equal coefficients before derivations: $u_{1}=u_{2} / \sqrt{w^{2}+d} ; v_{1}=v_{2} / \sqrt{w^{2}-d}$. As a consequence of this deformation any further rotations do not change the quadratic form of the derivations. The third step is rotation of coordinates on the angle $\alpha_{3}$ which diagonalizes the $u, v$ quadratic form. Coefficients before $u_{3} v_{3}$ terms equal zero if the angle $\alpha_{3}$ satisfies the condition

$$
\begin{gather*}
\cos 2 \alpha_{3}=\frac{G}{\sqrt{4\left(b_{u}-b_{v}\right)^{2}\left(w^{4}-d^{2}\right)+G^{2}}} \\
G=\left(b_{u}+b_{v}-4 d\right)\left(w^{2}+d\right)-\left(b_{u}+b_{v}+4 d\right)\left(w^{2}-d\right) \tag{9}
\end{gather*}
$$

As result of all transformations, the final view of equations (6) is:

$$
\begin{gather*}
v_{3}^{\prime \prime}+\frac{1}{\lambda_{+}^{2}} v_{3}-\frac{1}{3} b_{v 3} v_{3}^{3}+\mathrm{O}\left(u_{3}\right)=0 \\
u_{3}^{\prime \prime}+\frac{1}{\lambda_{-}^{2}} u_{3}+b_{u v 2} u_{3} v_{3}^{2}+b_{u 0 v 3} v_{3}^{3}+\mathrm{O}\left(u_{3}^{2}\right)=0 \tag{10}
\end{gather*}
$$

Here characteristic dimensionless lengths are

$$
\begin{gather*}
\lambda_{ \pm}^{2}=\frac{\sqrt{4\left(b_{u}-b_{v}\right)^{2}\left(w^{4}-d^{2}\right)+G^{2}} \pm G_{+}}{4\left(b_{u} b_{v}-4 d^{2}\right)} \\
G_{+}=\left(b_{u}+b_{v}-4 d\right)\left(w^{2}+d\right)+\left(b_{u}+b_{v}+4 d\right)\left(w^{2}-d\right) \tag{11}
\end{gather*}
$$

The inequality $\lambda_{+} \gg \lambda_{-}$is satisfied. This means that normal variable $v_{3}$ is considerably softer than $u_{3}$ one. Therefore, a variation interval for $v_{3}$ is considerably wider than that for $u_{3}$ : we can write an inequality $v_{3} \gg u_{3}$ and neglect the higher powers $\mathrm{O}\left(u_{3}\right)$ in equations (10). So the first equation in the nonlinear system (10) becomes independent. As one can see in relations (9), (11) and the definition of $v_{2}$, the obtained equations for nonlinear waves describe a situation with threshold velocity $w^{2}>d$.

Coefficients $b_{v 3}, b_{u v 2}, b_{u 0 v 3}$ before the nonlinear terms are very cumbersome to write here. Nevertheless, their physical sense is obvious. In the first equation, the term with coefficient $b_{v 3}$ describes nonlinearity of a soft normal mode with considerably large amplitude. In the second equation, the term with coefficient $b_{u v 2}$ slightly renormalizes the fast characteristic length $\lambda_{-}$(or frequency) in dependence on the slow variable $v_{3}$. In the second equation, the term with coefficient $b_{u 003}$ slightly shifts the equilibrium position of the fast oscillator $u_{3}$ in dependence on the slow variable $v_{3}$. According to the second equation of the system (10) the variable $u_{3}$ oscillates with a relatively small space period $\lambda_{-}$ accounting for the influence of $v_{3}$.

The first equation in (10) can be transformed into a nonlinear Schrödinger one with well known solutions. The first equation in system (10) has negative parameter of nonlinearity, its periodic solution can be written according to [12] as

$$
\begin{align*}
v_{3}(\zeta) & =\frac{k \sqrt{g}}{4 \delta_{s}} \operatorname{sn}\left[\frac{g \zeta}{4 \delta_{s}}, k\right] ; \quad k^{2}=\frac{\gamma-\sqrt{\gamma^{2}-\gamma_{0}^{2}}}{\gamma+\sqrt{\gamma^{2}-\gamma_{0}^{2}}} \\
\delta_{s} & =K(k)-E(k) ; \quad g=\frac{b_{v 3}}{3} ; \gamma=\frac{3}{2 b_{v 3} \lambda_{+}^{2}} \tag{12}
\end{align*}
$$

Here $K(k), E(k)$ are the complete elliptic integrals of the first and second order with elliptic module $k$, and $\operatorname{sn}(x, k)$ is the elliptic sinus, $\gamma_{0}^{2}$ is the integral of equation (10a) which has the sense of energy. At $\gamma_{0} \rightarrow \gamma$ for most of the time the molecules are far from the equilibrium positions (close to the saddle points of the effective potential [10]). At $\gamma_{0}=\gamma$ the solution (12) transforms into a kink.

## 5. Conclusion

For the first time the nonlinear excitations close to the point of orientational melting were considered. We use the strong anisotropy of the molecular rotation on the plane of the angles ('valleys'). Building of the normal coordinates on the plane of the angles gives the possibility of splitting equations for linear and nonlinear molecular chain oscillations. The linear oscillations correspond to a stiffer subsystem and are stable. The nonlinear oscillations correspond to a softer subsystem and, therefore, easily reach an unstable states (bifurcation points of the dynamical system).

It would be interesting to apply the obtained results in the nonlinear dynamics of molecular crystals to investigate the thermodynamics and kinetic properties in regions close to orientational melting.

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